Advanced Analysis Methodologies



Censored Data

- Converting to continuous data often presents analysis challenges
- For example, if we use detection range, how do we account for nondetects in the analysis
- Censored data provides a solution

• Generalized Linear Models

- System performance is often best characterized by non-normal data
 » Time
 - » Accuracy
 - » Pass/Fail
- Generalized linear models provide a more flexible analysis framework to handle these non-normal outcomes.

• Bayesian Methodologies

- Allow for the incorporation of multiple sources of information, when it is appropriate
- Provide methodologies for finding confidence intervals when there are zero observations

IDA Motivating Example: Submarine Detection Time

System Description

- Sonar system replica in a laboratory on which hydrophone-level data, recorded during real-world interactions can be played back in real-time.
- System can process the raw hydrophone-level data with any desired version of the sonar software.
- Upgrade every two years; test to determine new version is better
- Advanced Processor Build (APB) 2011 contains a potential advancement over APB 2009 (new detection method capability)



• **Response Variable:** Detection Time

Time from first appearance in recordings until operator detection » Failed operator detections resulted in *right censored data*

Factors:

- Operator proficiency (quantified score based on experience, time since last deployment, etc.)
- Submarine Type (SSN, SSK)
- System Software Version (APB 2009, APB 2011)
- Array Type (A, B)
- Target Loudness (Quiet, Loud)



• Detection time does not follow a normal distribution





Failed Detection Opportunities





- Advanced statistical modeling techniques incorporated all of the information across the operational space.
 - Generalized linear model with log-normal detection times
 - Censored data analysis accounts for non-detects
- All factors were significant predictors of the detection time

Factor/Model Term	Description of Effect	P-Value
Recognition Factor	Increased recognition factors resulted in shortened detection times	0.0227
APB	Detection time is shorter for APB-11	0.0025
Target Type	Detection time is shorter for SSN targets	0.0004
Target Noise Level	Detection time is shorter for loud targets	0.0012
Array Type	Detection time is shorter for Array B	0.0006
Type* Noise		0.0628
Type* Array	Additional model terms improve predictions. Third	0.9091
Noise*Array	therefore all second order terms are retained.	0.8292
Type* Noise*Array		0.0675



Submarine Detection Time: Results



- Median detection times show a clear advantage of APB-11 over the legacy APB
- Confidence interval widths reflect weighting of data towards APB-11
- Statistical model provides insights in areas with limited data
 - Note median detection time in cases with heavy censoring is shifted higher



- Censored data = we didn't observe the detection directly, but we expect it will occur if the test had continued
 - We cannot make an exact measurement, but there is information we can use. The no detects are on the tail of the distribution!
 - Same concept as a time-terminated reliability trials (failure data)

Run No.	Result	Result Code	Timelines	Run No.	Time of Detection (hours after COMEX)
1	Detected Target	1	┝────	1	4.4
2	Detected Target	1	┝────◆	2	2.7
3	No detect	0	₩	3	>6.1
4	Detected Target	1	Ⅰ ———◆	4	2.5
5	Detected Target	1	▶	5	3.5
6	Detected Target	1	┣────◆	6	5.3
7	No detect	0	*	7	>6.2
8	No detect	0	₩	8	>5.8
9	Detected Target	1	┝───♦	9	1.8
10	Detected Target	1	┝────	10	2.7
			♦ = Detect 🗱 = No-Detect		



- Assume that the time data come from an underlying distribution, such as the log-normal distribution
 - Other distributions may apply you must consider carefully. See slide 4 where we did it for the submarine detection data
- That parameterization will enable us to <u>link</u> the time metric to the probability of detection metric.





- Example: Aircraft must detect the target within it's nominal time on station (6-hours)
 - Binomial metric was detect/non-detect within time-on-station
- If we determine the shape of this curve (i.e., determine the parameters of the PDF/CDF), we can use the time metric to determine the probability to detect!





Conceptualizing the Censored-Data Fit

- For non-censored measurements, the PDF fit is easy to conceptualize
- For censored measurements, the data can't define the PDF, but we know they contribute to the probability density beyond the censor point
- Example event from an OT:
 - No Detects (Detect Time > 6 hours) lie somewhere on the tail of the distribution.
 - Detect will eventually occur sometime after 6 hours, pushing the distribution curve to the right
 - Mathematically, there are ways of calculating the shifted distribution.





IDA Characterizing Performance with Censored Data

- Now let's employ DOE...
- Consider a test with 16 runs
 - **<u>Two</u>** factors examined in the test
 - Run Matrix:

	Target Fast	Target Slow	Totals
Test Location 1	4	4	8
Test Location 2	4	4	8
	8	8	16

- Detection Results:

	Target Fast	Target Slow	Totals
Test Location 1	3/4	4/4	7/8 (0.875)
Test Location 2	3/4	1/4	4/8 (0.5)
	6/8 (0.75)	5/8 (0.63)	

IDA Attempt to Characterize Performance

- As expected, 4 runs in each condition is *insufficient* to characterize performance with a binomial metric
- Cannot tell which factor drives performance or which conditions will cause the system to meet/fail requirements
- Likely will only report a 'roll-up' of 11/16
 - 90% confidence interval:
 [0.45, 0.87]



IDA

Characterizing Performance Better

- Measure *time-to-detect* in lieu of binomial metric, employ censored data analysis...
- Significant reduction in confidence intervals!
 - Now can tell significant differences in performance
 - » E.g., system is performing poorly in Location 2 against slow targets
 - We can confidently conclude performance is above threshold in three conditions
 - » Not possible with a "probability to detect" analysis!





- Many binary metrics can be recast using a continuous metrics
 - Care is needed, does not always work, but...
 - Cost saving potential is too great not to consider it!
- With Censored-data analysis methods, we retain the binary information (non-detects), but gain the benefits of using a continuous metric
 - Better information for the warfighter
 - Maintains a link to the "Probability of..." requirements
- Converting to the censored-continuous metric maximizes
 test efficiency
 - In some cases, as much as 50% reduction in test costs for near identical results in percentile estimates
 - Benefit is greatest when the goal is to identify significant factors (characterize performance)



- There are many classes of statistical models:
 - General linear models (normal distribution)
 - Generalized linear models (Exponential family)
 - » Provides a simplified framework for numerically maximizing the likelihood
 - Location-scale regression (location scale, log-location scale)
 - Nonlinear regression (almost everything else)
- These regression analyses are a logical extension of standard statistical regression analysis
- However, methods presented here are more general
 - Data not necessarily normal
 - Data may not have constant variance
 - Lind between data and response may not be linear
- Practical T&E problems often cannot be solved with straightforward regression analysis

A Model Specification: GLM versus Generalized Linear Model

- General Linear Model (e.g., regression)
 - Model: $f(y) \sim Normal(\mu, \sigma)$

$$\mu = \beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_i x_i^2 + \sum_{i=1}^{k-1} \sum_{j=i+1}^k \beta_{ij} x_i x_j + h.o.t.$$

- Where, k is the number of factors and h.o.t. are higher order terms.
- Generalized Linear Model

– Model:

g⁻() is the inverse "link function" – it literally links the factors to the expected value of the response $f(y) \sim ExponentialFamilyDistribution(\alpha, \beta)$ $E(Y) = \mu = f(\alpha, \beta)$ $\mu = g^{-1} \left(\beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_i x_i^2 + \sum_{i=1}^{k-1} \sum_{j=i+1}^k \beta_{ij} x_i x_j + h.o.t\right)$



Exponential Family

- Class of distributions that provides the basis for Generalized Linear Models
- Distributions include:
 - Continuous
 - » Normal
 - » Log-normal
 - » Beta



Gamma Distribution



 Provide flexible shapes that can be used to describe almost any type of data!

IDA Pass/Fail Analysis: A Second Motivating Example

- System's goal is to maintain a lock on a moving target
- Response Variable: Maintain track? (Yes/No)
 - Debatable if a continuous metric could have replaced this binary response. However, no continuous metric was tracked during the test, so we are stuck analyzing pass/fail response.
- Factors:
 - Target Size (small/large)
 - Target Speed (slow/fast)
 - Time of Day (day/night)
 - Target Aspect (frontal/quarter)
 - Maneuvering (yes/no)
- Generalized linear models can be used to fit logistic and probit regression under the same framework!



• Logistic Regression Model:

$$f(y) \sim Binomial(n, p)$$

$$\mu = np$$

$$\mu = \frac{\exp\left(\beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_i x_i^2 + \sum_{i=1}^{k-1} \sum_{j=i+1}^k \beta_{ij} x_i x_j + h.o.t\right)}{1 + \exp\left(\beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_i x_i^2 + \sum_{i=1}^{k-1} \sum_{j=i+1}^k \beta_{ij} x_i x_j + h.o.t\right)}$$



Summarizing Results





Parametric Statistical Model Hierarchy

• There is a model for every situation!



- x2 for Bayesian versions of these model forms, which can also incorporate prior knowledge
- Note, Bayesian methodologies can make analysis easier by avoiding the complex optimization problem.



Bayesian Methodology – Overview





Motivating Example: Stryker Reliability Analysis

- Statistical methods (including DOE) apply to reliability data as well as performance data
- Stryker Retrospective Case Study
 - Infantry Carrier Vehicle (ICV) the infantry/mission-vehicle type
 - Base vehicle for eight separate configurations
 - IOT&E Results:

Stryker Reliability by Variant using Operational Test Data						
	Total Miles	System		MMBSA	MMBSA	
Vehicle Variant	Driven	Aborts	MMBSA	95% LCL	95% UCL	
Antitank Guided Missile Vehicle (ATGMV)	10334	12	861	493	1667	
Commander's Vehicle (CV)	8494	1	8494	1525	335495	
Engineer Squad Vehicle (ESV)	3771	13	290	170	545	
Fire Support Vehicle (FSV)	2306	1	2306	414	91082	
Infantry Carrier Vehicle (ICV)	29982	35	857	616	1230	
Mortar Carrier Vehicle (MCV)	4521	4	1130	441	4148	
Medical Evacuation Vehicle (MEV)	1967	0	-	657	-	
Reconnaissance Vehicle (RV)	5374	2	2687	744	22187	
Total	66749	68	982	774	1264	

• Results do not leverage DT data or relationships between vehicles



The Stryker Reliability Data Set





Bayesian Analysis for Incorporating Developmental Test

• Informative Priors

- Based on subject matter expertise (there will be a degradation in OT reliability)
 - » Data is already included in model
- Hierarchical Models
 - Assumes the parameters are related, the data tells us how closely related
 - Hierarchical models for the Stryker case study allow us to estimate MEV reliability based on other data





Stryker Reliability Results





- Provide very flexible analysis methods
- Priors allow us to consider other types of data, basing decisions on all available information about a system
- Methods can easily be extended to incorporate other situations:
 - Kill chain analysis
 - Complex system structures reliability analysis
 - Incorporate any relevant prior testing, modeling and simulation, or engineering analysis